

## Jim Dart Urban Planning Prize

Code:	P195
Faculty:	Engineering and Design
Applicable study:	URBPLAN 715
Closing date:	By nomination
Tenure:	
For:	Prize
Number on offer:	One
Offer rate:	Annually
Value:	\$1,200

## Description

This Prize was established in 2019 in memory of Jim Dart (1928-2018), lecturer in Town Planning 1962-1993. While lecturing at the University of Auckland, he founded the Town Planning Quarterly and after retiring became a commissioner on the Planning Tribunal (later the Environment Court).

The main purpose of the Prize is to support emerging planners by recognising and rewarding the student enrolled in the Masters of Urban Planning (Professional) who completed the best dissertation dealing with environmental, conservation, resilience or sustainability issues.

## Selection process

- Nomination is made to the Scholarships Office
- The Prize is awarded by the University of Auckland Council on the recommendation of the Head of the School of Architecture and Planning

## Regulations

- 1. The Prize will be known as the Jim Dart Urban Planning Prize.
- 2. One Prize will be awarded annually and will be of the value of \$1,200.
- 3. The Prize will be awarded to the student who submitted the best dissertation in URBPLAN 715 Urban Planning Research Dissertation relating to environmental, conservation, resilience or sustainability issues. As a minimum standard, the student must have achieved an A- grade.
- 4. The Prize will be awarded by the University of Auckland Council upon the recommendation of the Head of the School of Architecture and Planning (or nominee).
- 5. In the event of a tie, the Head of the School of Architecture and Planning (or nominee) will determine whether the Prize may be shared.
- 6. The University of Auckland Council has the power to amend or vary these regulations provided that there is no departure from the main purpose of the Prize.
- 7. The University of Auckland Council is not obliged to make an award if in any year there are no candidates of sufficient

merit.